

# AUTOMATIC FREIGHT TRAIN IS CREWLESS



Automatic train operation around the clock, 24 hours daily, seven days per week the year 'round, is enabling the Iron Ore Co. of Canada to haul 20 million long tons annually of crude iron ore from loading pockets at the mine site to a dumper at the crusher site. Four 18-car ore trains are shuttling back and forth along a 5.7-mile line, each taking approximately 80 minutes for the round trip from loader to crusher. The single-track railway, located near Labrador City, is capable of handling 55,000 long tons (2,200 lb per ton) of crude ore per day. Each of the four trains is powered by a conventional GP-9 diesel-electric locomotive. The automation controls—built by General Railway Signal Co.—provide for completely automatic, simultaneous operation of four trains.

The operation of each locomotive is directed automatically from the wayside by coded AC current. The code consists of AC energy at 60 cycles that is interrupted 37.5 (service brakes), 75 (7.5 mph), 120 (15 mph), 180 (30 mph), or 270 (reversing) times per minute.

The code rate, as well as a lack of code, determines the nature of each command given to a train.

The inching ( $\frac{1}{8}$  to  $\frac{3}{8}$  mph) or slow speed, while loading and while precision spotting for dumping, is controlled by tone modulated 960-cycle carrier signals. These signals are applied to wire loops between the rails.

The AC coded controls and tone controls, or commands, are transmitted continuously in the rails toward the movement of the train, providing a positive and continuous check of track conditions, such as broken rails, switch position, or presence of other trains. On the train, these commands are picked up by receivers, inductively coupled to the rails. The commands are compared with actual train speed, as detected by an electronic speed governor. The resultant output is then converted to relay operation, automatically controlling the throttle and brakes in a proper manner for best locomotive handling.

Each train is arranged so that its locomotive pulls the loaded cars to the dumper (crusher) and pushes the emp-

ties back to the loader at the mine. Since the locomotive is always on the dumper end of the train, a special car on each train is also equipped with code-receiving equipment, as this car is leading when empties are pushed back to the loader.

At the loading point, the automated locomotive pushes the empties into a tunnel, stops, reverses, and draws them slowly out as they are loaded from a chute in the tunnel roof.

When the train is loaded, the loader operator pushes a button to send the train on its six-mile automatic trip back to the dumper (crusher) at speeds up to 30 mph. Before the train starts, however, the block system checks ahead to the siding to determine whether it is safe for the train to proceed. Loaded trains operate on the mainline only, and empty trains take the mainline or the siding. Under ideal speed conditions, and for optimum performance, each loaded train makes a nonstop meet with an empty train at the passing siding near the loaders.

A complete cycle of normal operation

for four ore trains consists of the following procedure:

(1) Loaded train A starts for the dumper, while train B is being loaded, train D is being unloaded, and empty train C is enroute to the loader.

(2) Loaded train A makes a nonstop meet with empty train C, while loading and unloading of the other trains continue.

(3) Loaded train A arrives at the dumper as empty train D departs. Trains B and C are both now being loaded.

(4) Empty train D starts back to the loader as train A starts to unload.

(5) Conditions are the same as in step 1, except loaded train B is now ready to start for the dumper.

The detailed track diagram shows all of the possible codes that can be ap-

plied to the rails, one at a time in a given track section. In order to visualize the operation in greater detail, assume that the same conditions exist as shown in the simplified track diagrams showing the cycle of operation.

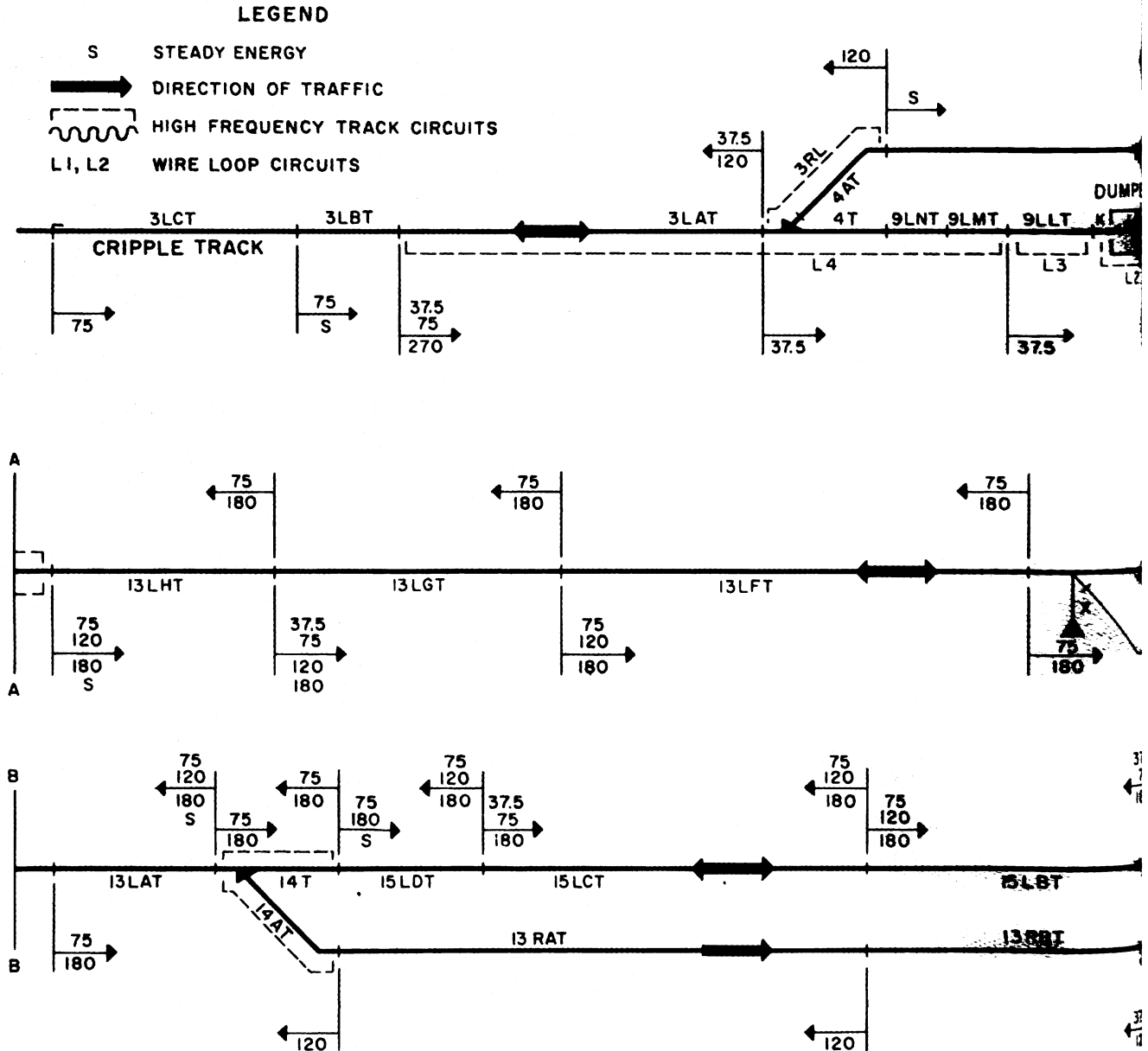
Train C is receiving a 180 code and is proceeding northbound on the single track. Loaded train A has been released by the loader operator to the automatic system. It receives a 120 code, which causes it to proceed over switch 18 reverse at 15 mph. It then slows to 7.5 mph when receiving the 75 code in approach to switch 14.

Assuming a nonstop meet, northbound train C on the single track receives a 120 code in approach to switch 14, and moves over the switch reverse at 15 mph. If track conditions permit, train C continues at this speed over

switches 16 to 18 reverse to the empty loader. Meanwhile, train A receives the 180 code and proceeds southward at 30 mph on the single track to the dumper. It receives the 120 code in approach to switch 10 and reduces speed to 15 mph. If the dumper is occupied, train A receives the 37.5 code and stops at a point 1,400 ft from the dumper location. If train D has previously left the dumper, train A would not stop until within 200 ft of the dumper location.

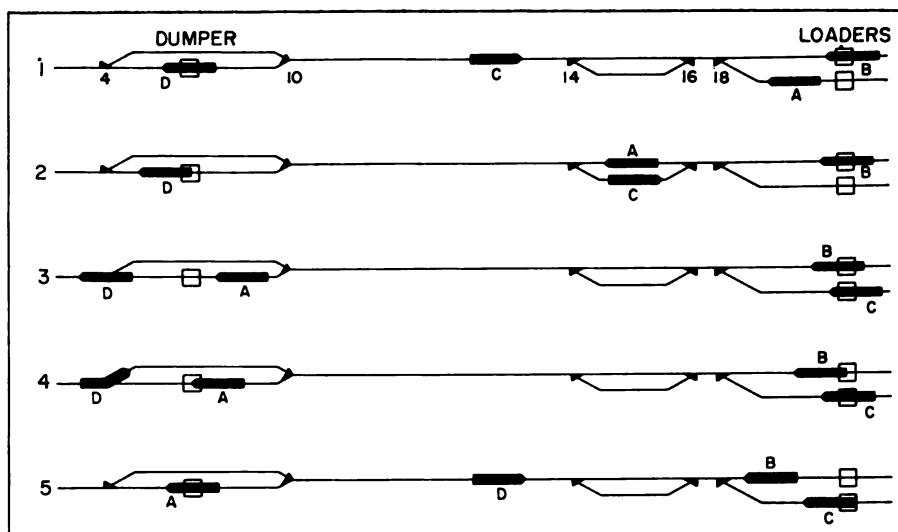
Automatic spotting at the dumper is accomplished by applying modulated carrier frequency to wire loops L1, L2, L3 and L4, and applying the 37.5 code to the rails. The 37.5 code is used to cause the train to stop should the modulated carrier signals be cut off.

When ready for train A, the dumper

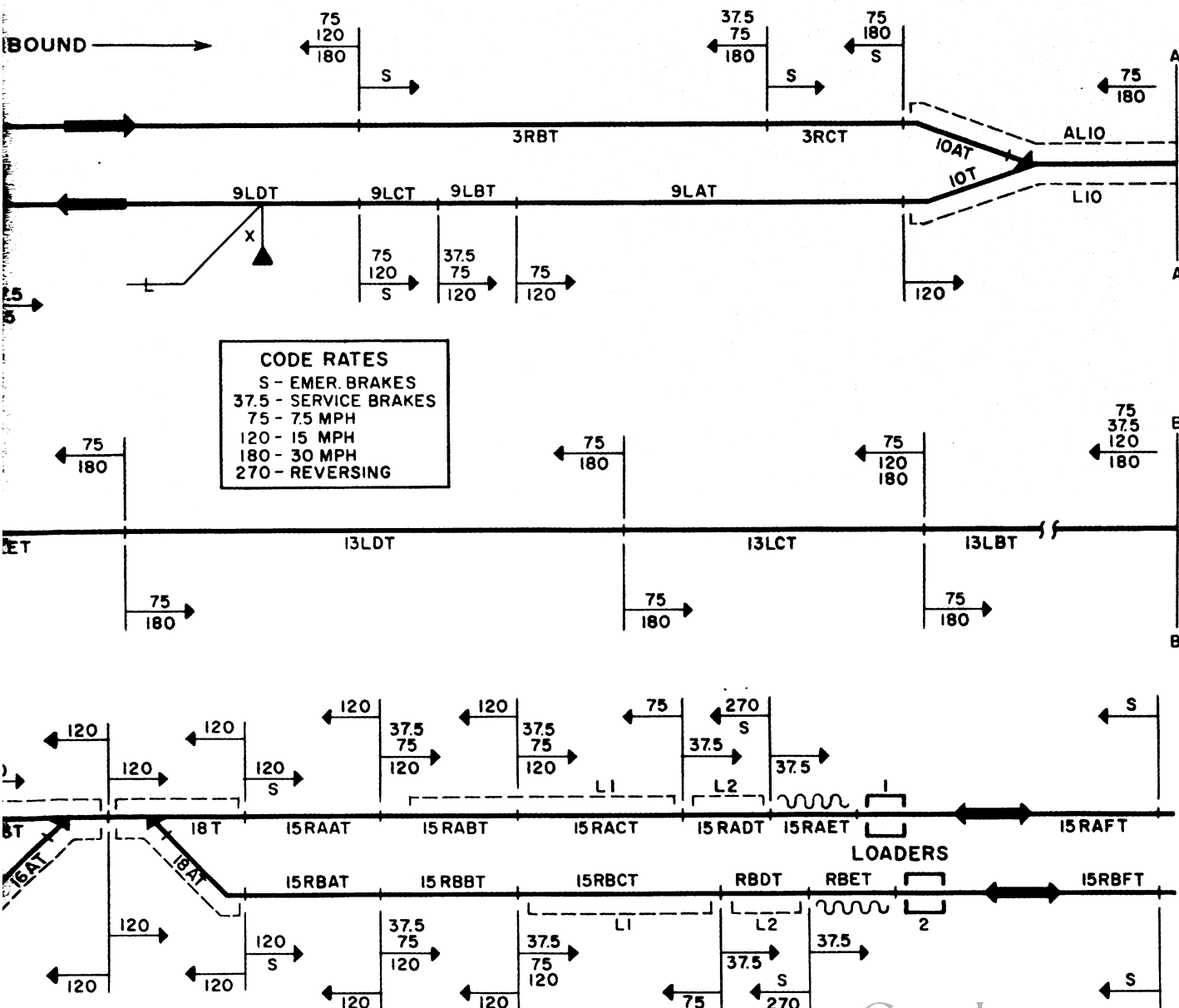


erator pushes his release train push-  
 button, causing the loaded train to au-  
 tomatically advance at 2 mph to a point  
 where the locomotive brakes are ap-  
 plied to stop the first car within the  
 dumping tolerance of  $\pm 7.5$  in. This  
 control automatically spots the cars and  
 provides interlocking to prevent train  
 movement during the dumping opera-  
 tion.

Track circuits determine when the  
 train is properly located for dumping.  
 Detector units determine whether the  
 train has stopped in the long side or the  
 short side of the tolerance. The brake  
 application point for stopping the next  
 train in the dumping cycle is then modi-  
 fied automatically to ensure that the  
 dumping of the cars will not gradually  
 fall out of tolerance with a consequent  
 loss of time to respot.



Block diagram shows how four ore trains are operated simultaneously.



## The editor's impressions of the automatic ore haulage operation.

Of the several things that impressed this visitor to this area—it is remote, being about 650 miles north of Montreal, Que., on the western edge of Labrador—the two outstanding are the magnitude of the job of mining the ore, it's earth moving on a vast scale, and how much conventional equipment was utilized in the automatic train operation. This latter fact means that a more widespread application of ATO is possible than has been heretofore realized.

The amount of material to be moved—55,000 tons daily—from mine to crusher necessitated a railway. The crude hematite ore has about 37% iron, which after crushing and concentrating, is brought up to 66% iron for shipment to Sept Iles. Just to give an idea of what's involved, here are some figures: An average of two feet of overburden is washed off first. Next, holes are drilled for blasting; a normal blast, I was told, will loosen 300,000 tons of crude ore. The ore is loaded by Marion electric shovels with 10-cu yd buckets into Euclid tractor trailers holding 100 tons. Driven down to the loading site, these trailers are side dumped into a hopper. When in full operation, IOC will have three shovels and

15 trucks in service at a time, with one shovel and five trucks out for servicing.

The crude ore, which may be in chunks up to 4 ft in diameter, is loaded into the 100-ton ore cars for hauling to the crusher or dumper. Here an initial crusher chews up the ore into 6-in. bites. Next the ore travels through six airfall mills, which use steel balls to grind the ore, and finally the crude ore passes through three stages of spirals or centrifuges for separating the iron from the rest of the material. From this stage powder-like material is 66% iron, which is loaded into Quebec North Shore & Labrador cars for hauling to Sept Iles. To sum it up, 200 tons of crude ore produce one ton of concentrate ready for shipment. IOC is now building a pelletizing plant at Labrador City, which when completed next spring, will produce about 5 million tons of 1/8-in. to 1/2-in. pellets. With the pellet plant in full operation, IOC will produce about two million tons of concentrate.

To handle this volume of material between mine and crusher, an automatic operation was necessary. It takes only one minute to dump the ore truck and one minute to load each railway car and another

Manual override of the spotting control is provided to stop the operation instantly and to control the train manually.

After all the cars have been dumped in train D, the train receives the 75 code and automatically proceeds at 7.5 mph until the last car is clear of junction switch 4. The switch then automatically throws reverse. Train D now receives the 270 code, transferring control from the locomotive to the tail car for the reverse movement and stopping the train.

The tail car receivers now pick up the 120 code, and the train proceeds over switch 4 reverse onto the run-around track. If the single track is not occupied, train D receives the 180 code and proceeds over switch 10 reverse and down the mainline at 30 mph.

Train C receives the 75 code after passing through switch 18 reverse, and thereby reduces speed to 7.5 mph. It then receives a reverse tone and stops about two or three car lengths from the loader. The 270 reversing code is then applied to transfer the control end from the tail car to the locomotive. A continuous tone, plus a 75 code, continues the operation of backing into the tunnel. As the train passes appropriately located insulated track joints, it

stops. With the first car behind the locomotive properly positioned, the operator pushes a button to start the train moving at inching speed out of the tunnel. By means of a tone-modulated carrier signal, the operator has a continuously variable control of this inching speed while loading. After loading, the operator returns control of train C to the automatic system.

Train B has, in the meantime, left the loader on its return trip to the dumper.

The train-carried equipment receives commands from the rails (coded AC signals or tone-modulated carrier signals) and, in turn, interprets these commands, causing the proper operation of the power and brake equipment. The train response is constantly monitored and compared with the commands. The moment that actual operation does not agree with the operation called for, corrective action is initiated automatically.

Receivers are mounted ahead of each of the two leading wheels, with the coils approximately centered over the rails and about 6 in. above the rail head. Direction selection components on the locomotive provide the choice of tail car receiver output or locomotive receiver output, depending upon the direction of travel.

On the locomotive, the signal from

the selected receivers passes through a tuner which (1) detects the rate code from the coded track circuits, or (2) detects the tone reception from the high-frequency track circuits. The tail control amplifier amplifies the rate code signal and produces rectified AC pulses which are fed to the direction selector.

On the tail car, only rate code pulses can be received. These pulses are amplified in the tail car train control amplifier, producing rectified AC output to operate a code-responsive relay. The coded signal is then transmitted via trainline cable to the automation equipment rack on the locomotive.

On the locomotive, the selected signal operates another code-responsive relay which pulses at the code rate being received from the rails. Coded information is then decoded to tell the train what action it should take. No code, or steady, means apply emergency brakes; a 37.5 code means apply service brakes; a 75 code means proceed at 7.5 mph; a 120 code means proceed at 15 mph; a 180 code means proceed at 30 mph; and a 270 code means reverse control ends.

The train speed indication portion of the equipment includes an axle generator, which is mounted on the journal box of the locomotive so that the rotating element is driven by the axle. The

ute for unloading from railway car into the  
sher. The 100-ton capacity railway cars are side  
nped.

The ore trains are operated push-pull with the  
-9 1,750-hp locomotives (previously in service on

QNS&L), hauling loaded trains down to the  
sher and pushing the empties back to the load-  
site at the mine. To alert personnel of a train's  
roach, headlights on the locomotive and tail  
are lighted continuously. Also, the locomotive  
l rings continuously and yellow revolving bea-  
l lights atop the locomotive and tail cars are  
nted.

The only time the locomotives will be taken out  
service is for refueling and inspections or other  
vicings. A red "emergency stop" pushbutton is  
unted on each side of the locomotive and may be  
erated by a person on the ground. A red indica-  
n lamp is lighted when this pushbutton has been  
erated. Alongside the red button is a black push-  
ton which, when operated, places the locomo-  
e on automatic control.

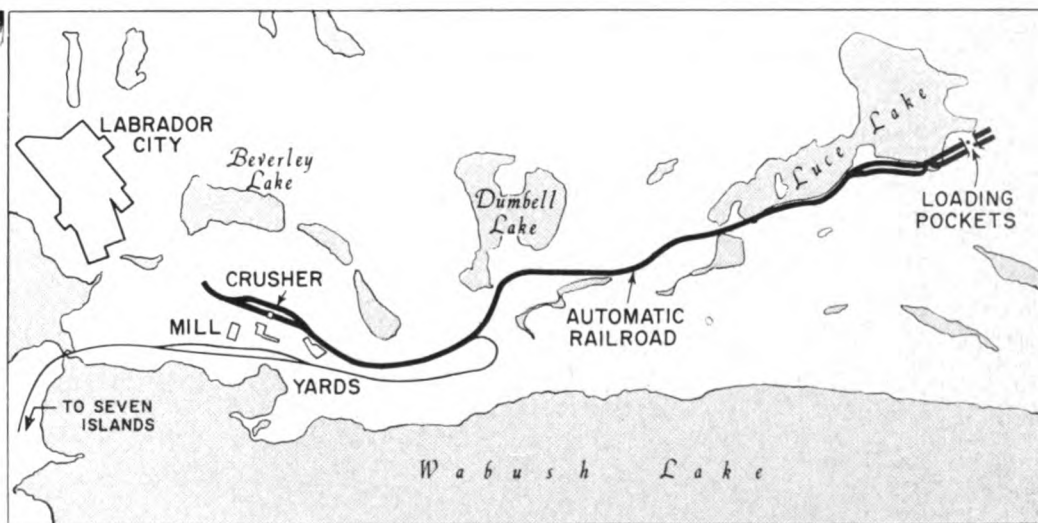
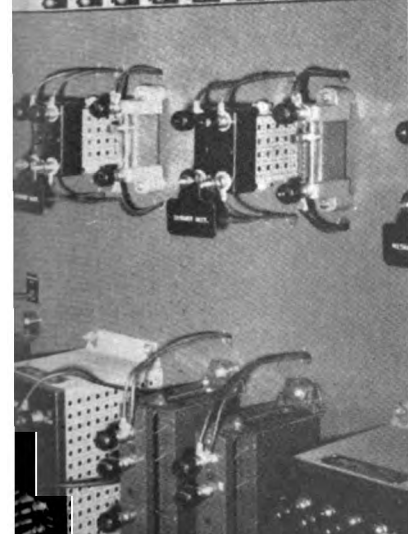
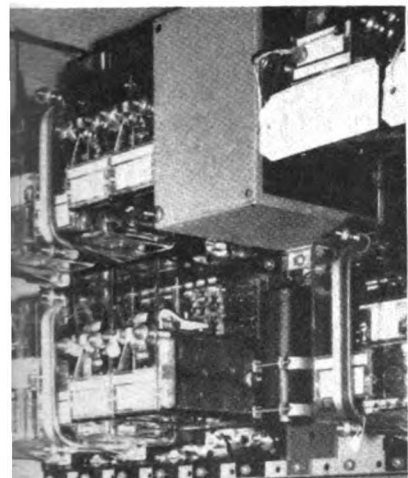
Upon looking into relay housings, I found con-  
ventional code transmitters, code following relays,

etc., normally used with coded track circuit in-  
stallations. To be sure, there are many new tech-  
niques and engineering that went into this ATO  
installation, but the amount of conventional equip-  
ment would seem to indicate that ATO has a  
bright future.

And it has, if the comments I heard from others  
who inspected this automatic ore haulage system  
are any indication of things to come. Several per-  
sons remarked that ATO is a natural for several  
similar mining operations that are now in service.  
One, for example, might be copper ore haulage on  
the Bingham & Garfield between the Bingham,  
Utah, copper mine and the smelter at Garfield,  
about 16 miles. General agreement was that the  
labor and political problems would be the most  
severe to overcome in the application of ATO.

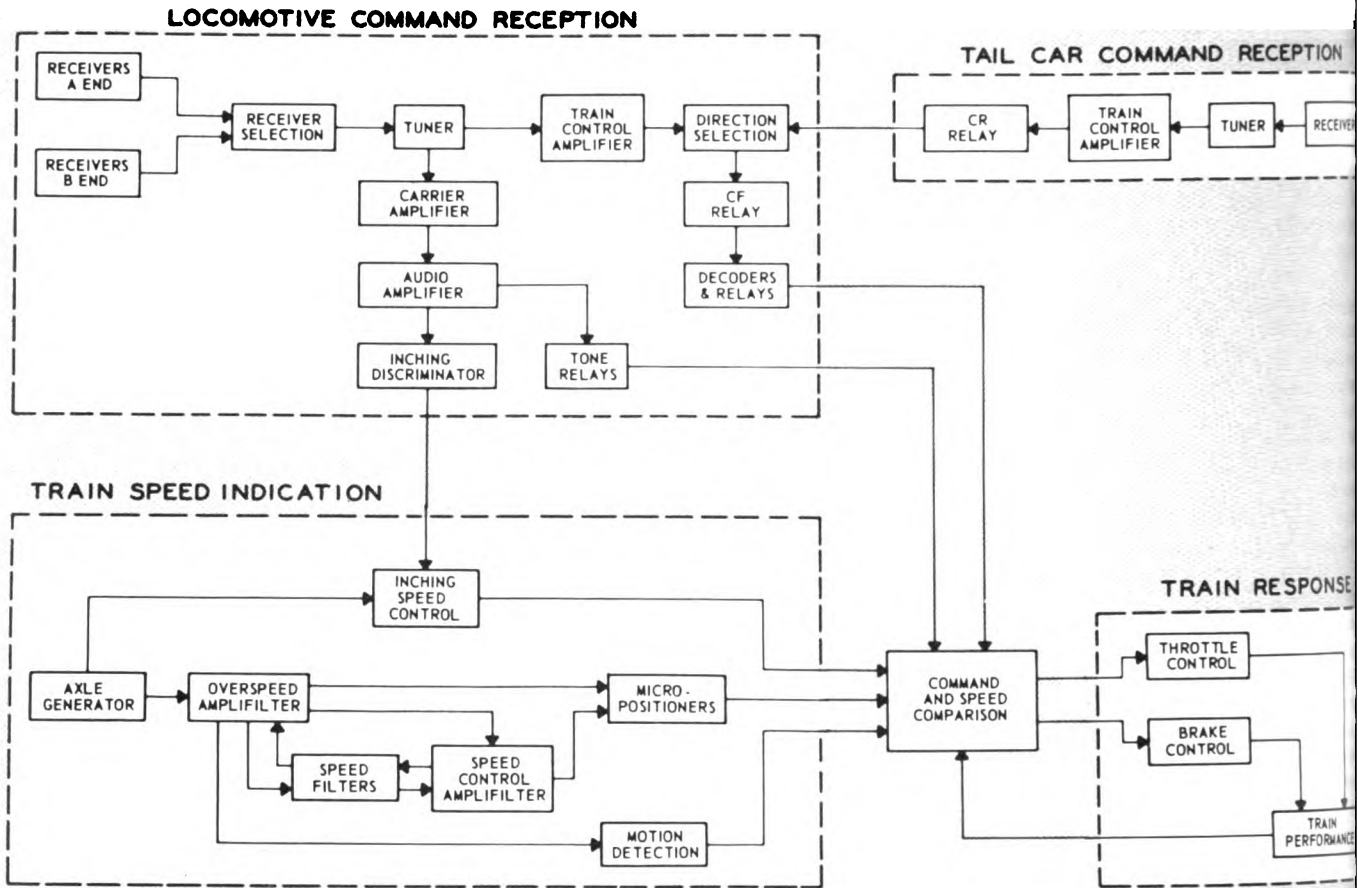
There was some comment that this ATO installa-  
tion might be extended to the 37-mile line that  
connects Labrador City to the mainline of the QNS&L,  
224 miles north of Sept Iles.

A lasting impression of this automatic ore haulage  
operation is that it operates smoothly and efficiently  
day-in and day-out without human attendants.

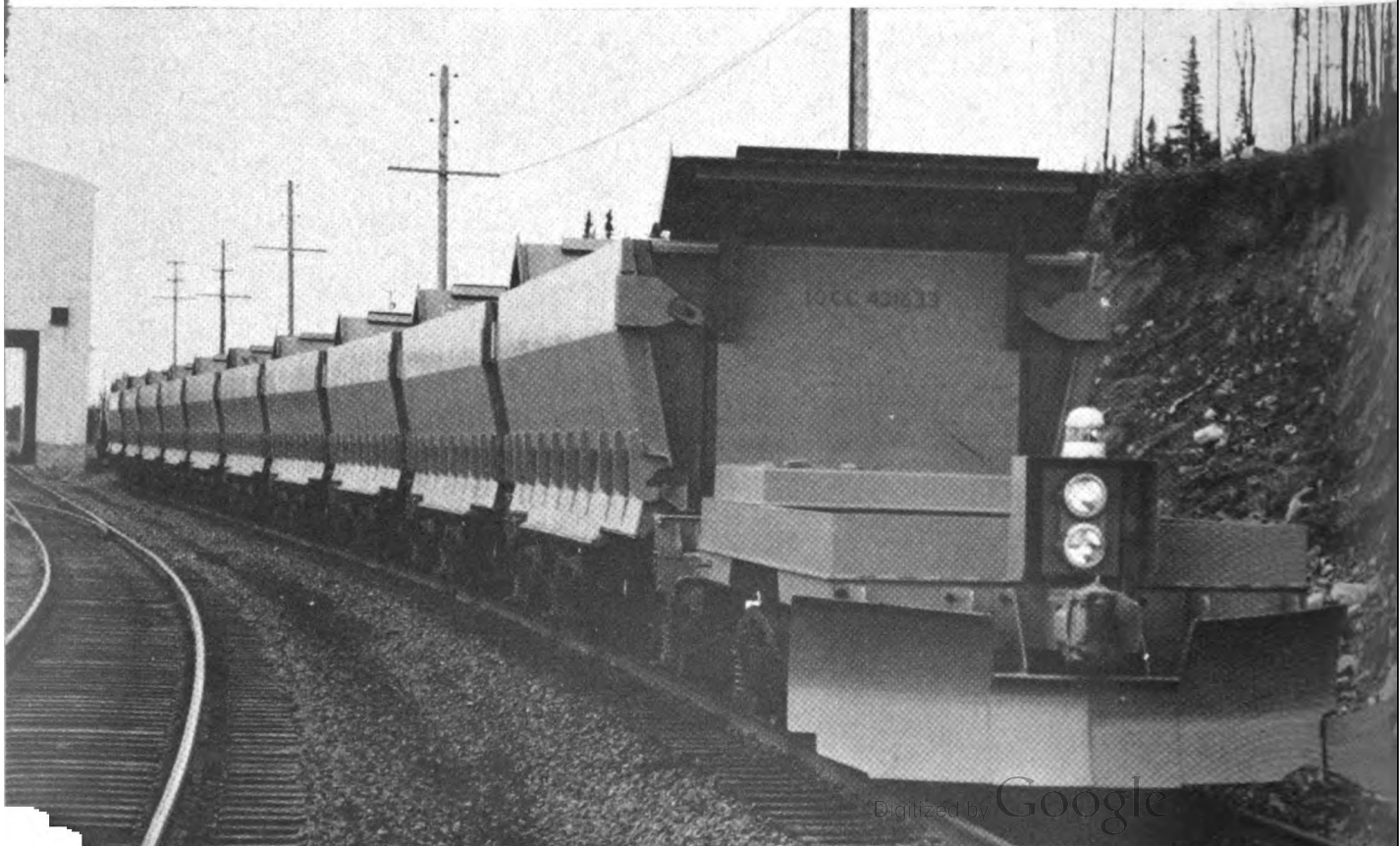


Four 18-car ore trains shuttle along this 5.7 mile railway between the loading pockets at the mine and the dumper at the crusher. The line has a continuous 0.2% descending grade from the pockets to the crusher. Concentrate ore is hauled by QNS&L to its Seven Islands port facilities.

Wayside equipment (left) includes transmitters for sending various codes into the track rails. The 60 cycle AC codes include 37.5 (service brakes), 75 (7.5 mph), 120 (15 mph), 180 (30 mph) or 270 (reversing). Tone-modulated 960 cps carrier signals are used for inching ( $\frac{1}{8}$  to  $\frac{3}{8}$  mph).



Block diagram shows arrangement of receiving, sensing and command units on locomotive and tail car (below).



erator produces an AC voltage with frequency proportional to the speed of the train.

Outputs of the axle generator and associated electronic equipment are used to detect (1) speeds  $\frac{1}{2}$  mph above and below the selected speed, (2) over-speed—when the train is 2 mph over the selected speed, and (3) motion—when the train is moving more than 1 mph.

The various outputs from the command reception and train speed indication sections of the train-carried equipment are compared in the command and speed comparison section. This section applies the proper commands to the locomotive brake and throttle controls. Locomotive performance is continuously checked to ascertain whether the train is responding according to the commands.

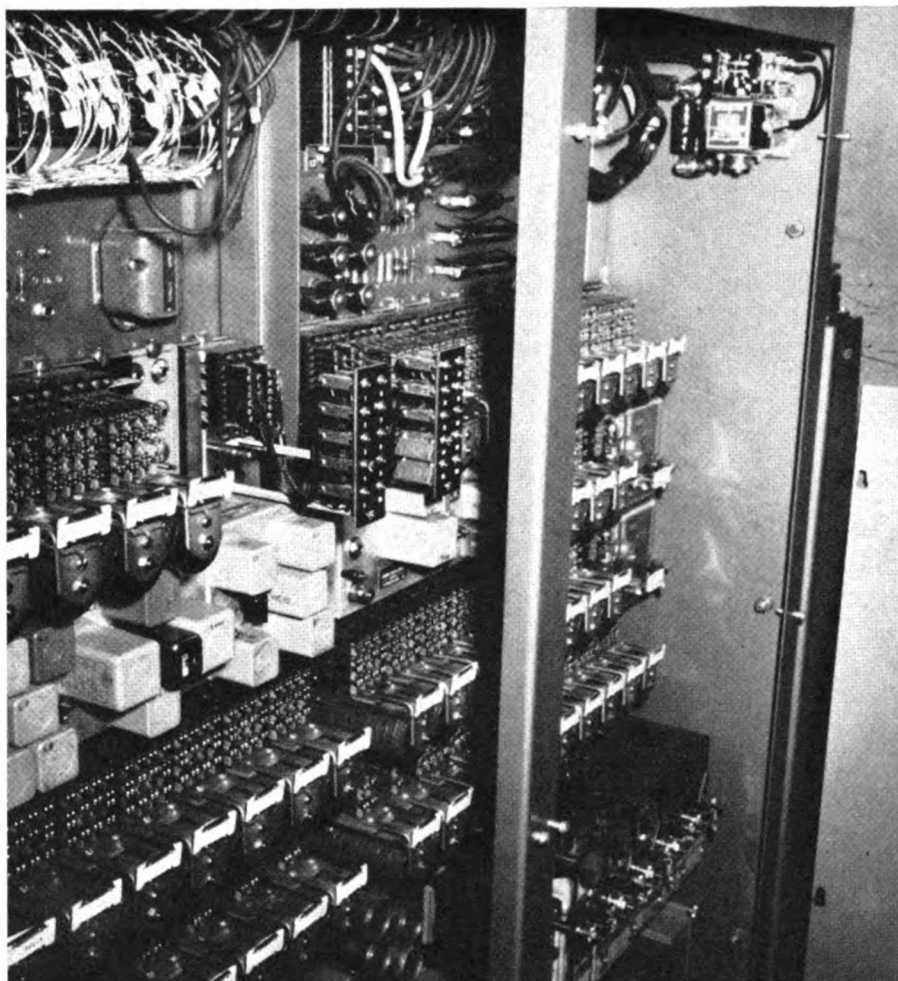
Train speed is maintained by cycling the power application up or down. For example, for maintaining 30 mph, the power is reduced at 30.5 mph. If the train reduces speed at 29.5, additional power is applied and the cycle is repeated. However, if the power is reduced on a train operating at 30.5 mph and its speed increases to 32 mph (due to a downgrade), service braking is applied to reduce the speed to 30 mph. The cycle is then repeated.

Continuously variable control is provided on the locomotive for the inching speed. This control, which is via a modulated-carrier signal picked up from the high frequency track circuits, is very precise. It controls train speeds on a continuously variable basis—between  $\frac{1}{8}$  and  $\frac{3}{8}$  mph  $\pm$  one-hundredth mph. The regular running speeds are maintained within  $\frac{1}{2}$  mph.

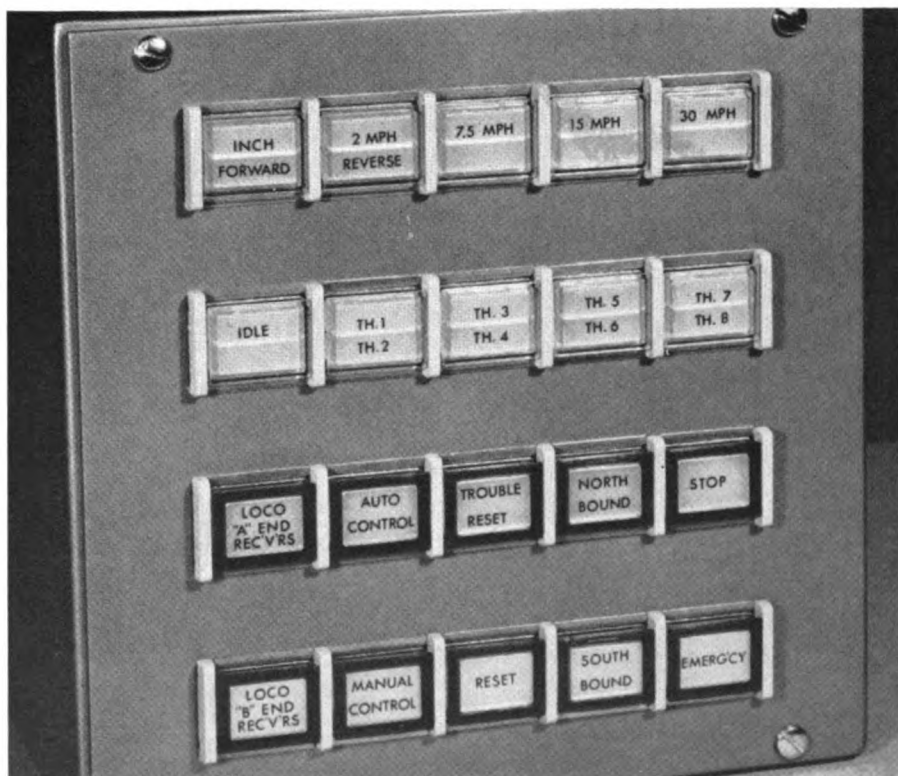
The brake equipment on the crewless train is electro-pneumatic straight air. In the shuttling operation brake equipment controls respond to coded commands to apply or release brakes. In other words, the brakes are either all on or all off. In inching or at low speed during loading or dumping, the special 960-cycle, tone-modulated code actuates brake controls that are sufficient to hold the brake shoes against the wheels, creating a dragging action that permits precise inching.

The manual-automatic changeover panel is used to put the locomotive back in ATO after it has been on manual control (when refueling or servicing).

The system is designed on fail-safe principles. Any failure of the continuous command stream causes a stop. Likewise, a central indicating and control console, located in the dumper building, provides complete facilities for normal override of all automatic operations as well as indications of train positions and system status. RSC



ATO equipment rack in the short hood of the locomotive carries the decoding and command control equipment, and features many plug-in units.



Manual-automatic changeover panel, also in the short hood, is used to put the locomotive back in automatic operation after it has been off ATO.