

sions of it with regard to power costs which are very misleading. Some have been imprudent enough to assert its economy for power purposes in connection with uneconomical water-power plants as the means of making such developments commercially available, and several large plants for cotton mills have been developed on this line with blindness as to their true commercial value.

For the purposes of this paper we will take up the investigation, by tabulated data, from the actual everyday operation of the plants, and we shall designate the two plants as No. 1 and No. 2. No. 1 is a steam-driven mill, having a steam plant geared up with ropes, heavy headed gearing, and large tapering shafts as such plants are usually geared up in the best practice of to-day. The steam engine is an 800-H. P. Corliss cross-compound, built in 1865, with cylinders 20 and 40 x 60-in. stroke, and a rope wheel 24 ft. pitch diameter, grooved for 26 1/2-in. ropes, weighing 35 tons. This engine is being operated at an exceptionally low cost per horse-power for steam. There was in the mill during the period for which comparison of power is made 11,776 spindles and 720 looms; all the spindles and preparatory machinery were run full, but the looms did not average more than 682 per day. No. 2 is an electric driven mill which rents its current from a central station and distributes it through a continuous reading wattmeter to four 150-H. P. inverted motors bolted to the ceiling in convenient locations for economical distribution of the power, and belted to the shafting. The mill has been in operation since Jan. 1, 1897. This mill had in operation during the period named above on an average of 12,448 spindles, with preparatory machinery and an average of 356 looms out of 500 in the mill. The weight of the shafting in the steam mill is approximately 136,000 lbs., and the electric mill 122,000 lbs.

From the data obtained from the steam-driven mill we have the following distribution of power during the test—for the steam-driven mill:

Total power.	Looms and shafting.	Friction.	H. P. spds.	Looms.
535	340	226	196	114

and for the electric driven mill:

Total power.	Looms and shafting.	Friction.	H. P. spds.	Looms.
418	206	149	208	60

Hence, the difference between 226 and 149 H. P., 77 H. P. must be credited to the electric mill in its present condition.*

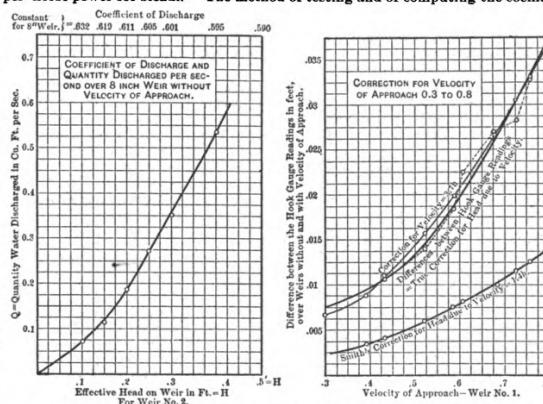
The following points from the foregoing can be stated as existing under the present conditions: the steam mill is operating under a disadvantage of an underloaded engine; the electric mill is operating under the disadvantage of driving more shafting per motor than it will when the full complement of machinery is installed.

The steam mill requires more supplies in the shape of oil, sizing for ropes, and other necessary incidentals due to the method of transmitting the power. The electric mill has cost nothing for its motors in six months of operation, not even the necessity of putting oil in the

author's opinion that this difference of power would not be exceeded, and he hopes subsequently to give more specific data from further experiment from the actual operation of these two plants under better conditions, viz., when both mills are completely filled with machinery and motors and engine run at their full load; also in obtaining the efficiency of direct connected engines and generators. It must be borne in mind that, unlike a machine shop and other manufacturing establishments, where a large amount of shafting is required to cover the ground and where intermittent power is used, a cotton mill drives in useful effect 95 per cent. of its shafting and uses actually in continuous operation almost the maximum power at all times.

TEST OF CENTRIFUGAL PUMP, ETC.—BY PROF. R. C. CARPENTER.

The paper first contained a description of the plant in which diagrams were used in explaining the details. The method of testing and of computing the coefficients



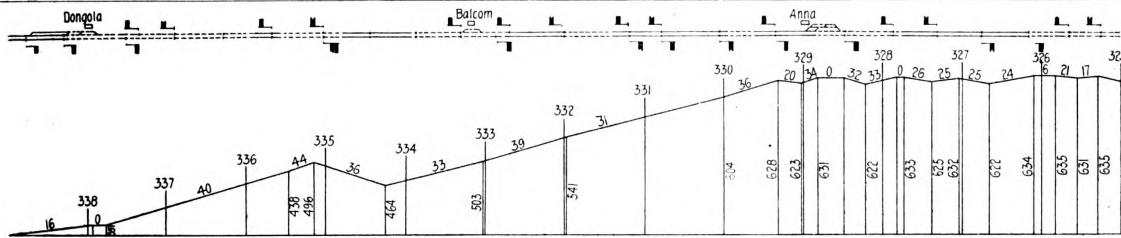


Fig. 1.—Profile and Diagram of the Line of the Illinois Central Railroad from Dongola to Bosky Dell, 28 miles—Continued in Fig. 2.

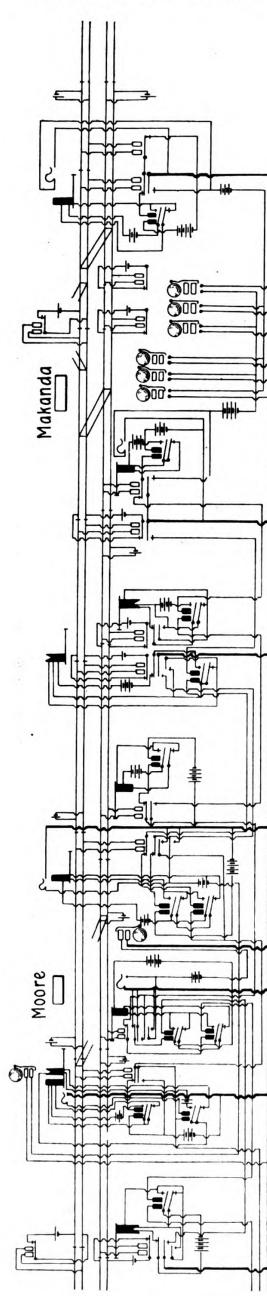
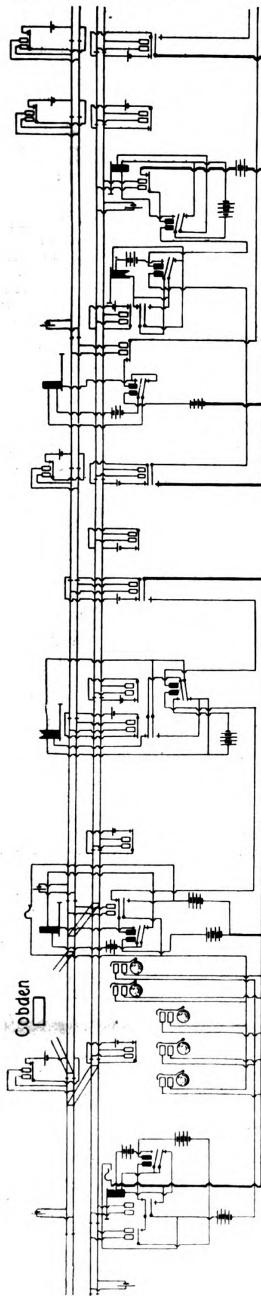
NOTE.—In the diagram each line represents a track; solid lines represent tangents and dotted lines curves.

at switches, and the manner in which the semaphores are operated. Until quite recently the practice has been to bond the joints by fastening the wires to the base of rail; but this has not proved altogether satisfactory, for the reason that bonds are sometimes forced out or broken, either by contact with the ties or by shearing off by the spikes in consequence of creeping of the rails. So much trouble was experienced from the latter cause on the approaches to the Cairo Bridge that it became necessary to provide some other form of bonding. The method

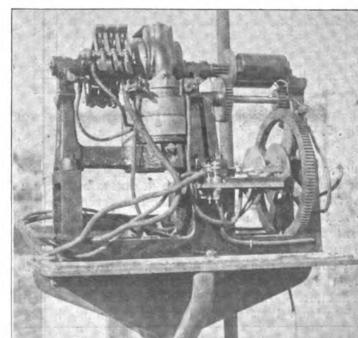
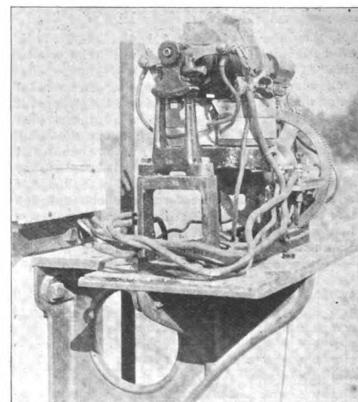
now pursued both on the bridge and on the St. Louis division is to bond through the web of the rail, using two wires, in substantially the same manner as that employed on electric street railroads. It obviates entirely the troubles experienced in the other method, and reduces the cost of replacements.

In the operation of the semaphore a one-sixth horse power motor is used, the power necessary to operate it, varying (according to the resistance of circuit) from 10 to 16 cells of Edison-Lalande type S battery. The

motor, as will be seen from the illustrations, is fastened to the side of the signal post, directly above the counter-weight lever. Attached to this lever is a stranded cable $\frac{1}{4}$ in. diameter, the other end of which, extending upward to the motor, is fastened to a drum keyed on to a shaft geared into the armature shaft as 25 to 1. The drum shaft is provided with a worm into which is geared a circuit-closing device for controlling the motor and brake circuits. On one end of the armature shaft is fastened a soft iron circular disk which, in connection with a high resistance coil, acts as a brake to stop the motor, there being lateral movement enough in the shaft to permit of the disk being attracted and held by the brake coils when they are energized. On the base supporting the motor are insulated strips forming a part of the circuit-closing device. The action of this circuit-closing device is such that when the block is unoccupied and no train is in the preliminary section the battery is on open circuit. When a train enters the preliminary section a circuit is automatically closed through the motor, which thereupon causes the signal to assume its clear position. Just before the signal reaches the clear position, the motor circuit is automatically broken, and a circuit is closed through the brake magnet coils, causing a retardation of the movement of the arm and bringing it without undue shock against the stop, where it is held by the brake magnet. In this connection it should be understood that the circular disk is never in contact with the brake magnet poles, the brake being purely magnetic and not a friction device. Thus there is no possibility of sticking due to residual magnetism. The signal remains in the clear position until the first wheels of the train pass the signal, when the brake magnet circuit is broken and the signal returns to the stop position; its speed, however, being retarded just before the signal arm reaches the stop by the counter current developed in a circuit at that time automatically closed through



Figs. 3 and 4.—Electric Circuits, Rail and Wire, for Automatic Block Signals, between Cobden and Makanda—Illinois Central Railroad.
The right-hand end of the upper diagram joins the left-hand end of the lower.



Figs. 5 and 6.—Side and End Views of Motor for Working Automatic Semaphore Signal.

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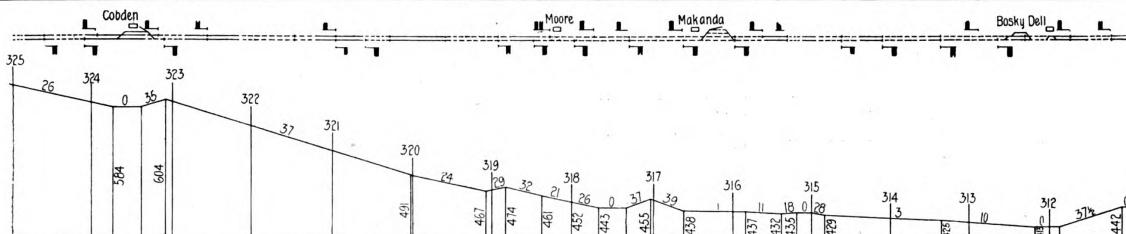


Fig. 2.—Continuation of Diagram Shown in Fig. 1.

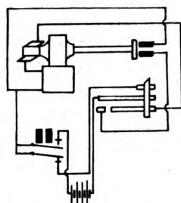


Fig. 10.—Wiring of Electric Motor.

the motor only. The wiring of the motor is shown in Fig. 10.

In considering the application of automatic signals generally, the important question is to determine their reliability and efficiency. With enclosed signals the apparatus directly controlling the signal is not subjected to wind, rain or snow, and the question of a normally danger or normally clear system becomes one of individual preference. With semaphores, however, the conditions are changed, and it becomes a matter of expediency that the signals be normally at danger. The actual time a signal is in the clear position (for train movements) is very much less than in the danger position (this will vary with volume of traffic); but assuming it to be relatively as one to five, the failure of apparatus should be on the side of safety, and the tendency of the signal arm to stick in sleet or snowy weather is certainly greatest in the position at which it is the longest time at rest, and in contending against such possibilities, it must be remembered that the failure to move from the stop or danger position is safe,

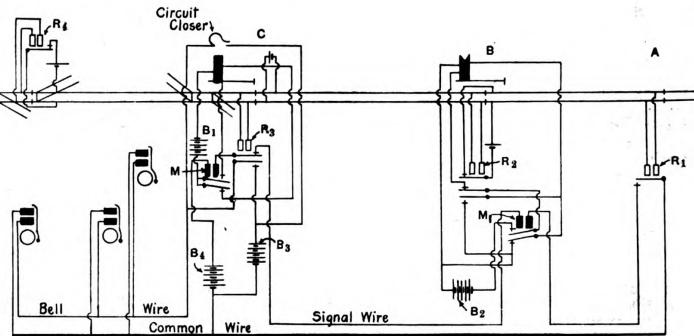


Fig. 5.—Electric Circuits for Automatic Signals for one Block Section.

while failure to move from the clear position is likely to be unsafe. It may be argued that the danger of failure is remote, but whether this be true or not the principle of keeping signals normally at danger is correct, and it presents no obstacle to economical and successful operation.

Number 8 E. B. B. iron wire is used for the line on the telegraph poles, and all batteries are placed underground; those for the track circuit in cast iron chutes and for the motors and switch bells in cedar tubes specially made for the purpose.

The cost of maintenance and operation of these signals, so far as it has been possible to judge from experience thus far, will be but little if any greater than that of disk signals.

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EXPLANATION OF DIAGRAM, FIG. 5.

A B, C D are sections of track constituting a block with its distant signal and preliminary circuit. *R₁*, *R₂*, *R₃*, *R₄* are track relays; *M* and *M₁* are relays directly controlling the motor circuit; *B₁* and *B₂* are the batteries operating the motors, *B₃* is the battery for operating the bells, and *B₄* is the battery for operating the relays *M* and *M₁*. All the track relays are normally closed and the relays *M* and *M₁* are normally open. The entrance of a train on the section *A B* shunts the track battery from track relay *R₁*, closing the path for battery *B₁* through back contact point of relay *R₁*, and thus energizing relays *M* and *M₁*. The energizing of relay *M* closes the front contact on that relay, thus completing the circuit for battery *B₁* through this contact and the home signal motor, thus pulling this signal to the clear position. A similar result follows with relay *M₁*, battery *B₂* and the distant signal. When the home signal is in the clear position a circuit is closed through the circuit closer, battery *B₃* and the bell magnets, causing the bells to sound at all switches in the section of track controlled by this signal. When the train enters the section *C D*, relay *R₂* is demagnetized and the distant signal arm resumes the horizontal position, this being effected by the breaking of the circuit for battery *B₂* through the opening of the front contact of this relay. The train entering section *C D* demagnetizes relay *R₃* and the home signal resumes the stop position by reason of the breaking of the circuit of battery *B₁* through the opening of the circuit through relay *M*, which is effected by the opening of one of the contact points on relay *R₄*. It will be noticed that the home signal is in the stop position and the circuit closer open; but the bells will continue to sound as long as the train is in the section *C D* because the circuit is completed through the back contact point of *R₄*, battery *B₃* and the bell magnet coils. When the train passes out of section *C D* all apparatus is restored to the normal position.

If, at the time a train passes *A* the block *C D* is occupied by a preceding train or car, or a switch is open, the demagnetization of *R₁* by the action of the wheels has no effect on relays *M* and *M₁*, for the circuit of battery *B₁* is held open at *R₄* by the preceding train (or car); and consequently the signals remain at danger and stop the train at *C*.

The lower armature of relay *M₁* when down—that is, when in the position that it takes when a train passes it and the signal at *B* goes to the horizontal position—closes a circuit through the path indicated by the

line shown at the underside of the arm of signal *B*. This circuit, which has no battery, runs through the motor, and the office of the lower armature of relay *M₁* is to close a circuit through the motor, outside of the motor battery, and thus aid in retarding the motion of the signal arm as it approaches the end of its stroke. The relation of relay *M₁* to the motor is shown in Fig. 10. Relay *M* has connections to its motor similar to those of relay *M₁*.

f, while a train is between *B* and *C*, a following train

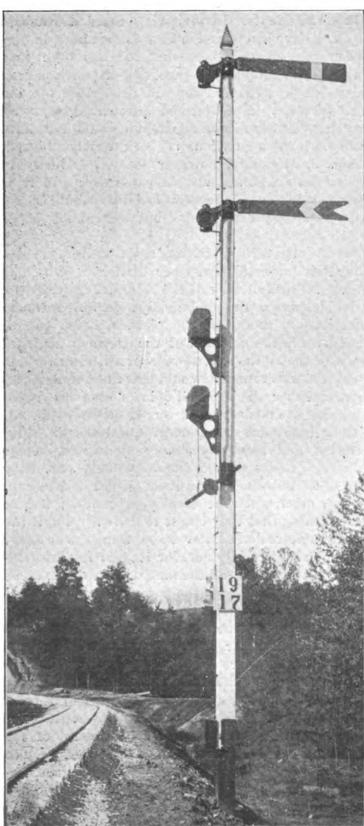


Fig. 6.—Automatic Semaphore Signal—Illinois Central Railroad.

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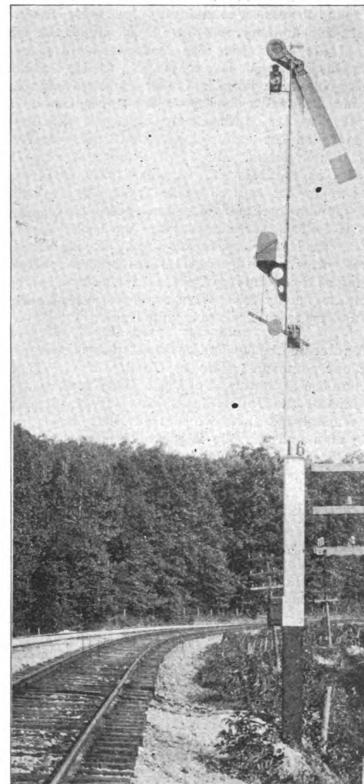


Fig. 7.

should pass *A*, this second train, by holding *M₁* closed, would prevent the closing of the no-battery circuit described in the preceding paragraph; to avoid this the dropping of the third armature of *R₂*, which is effected by the presence of the first train in the section *B C*, is made to close the no-battery circuit around *M₁*.

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